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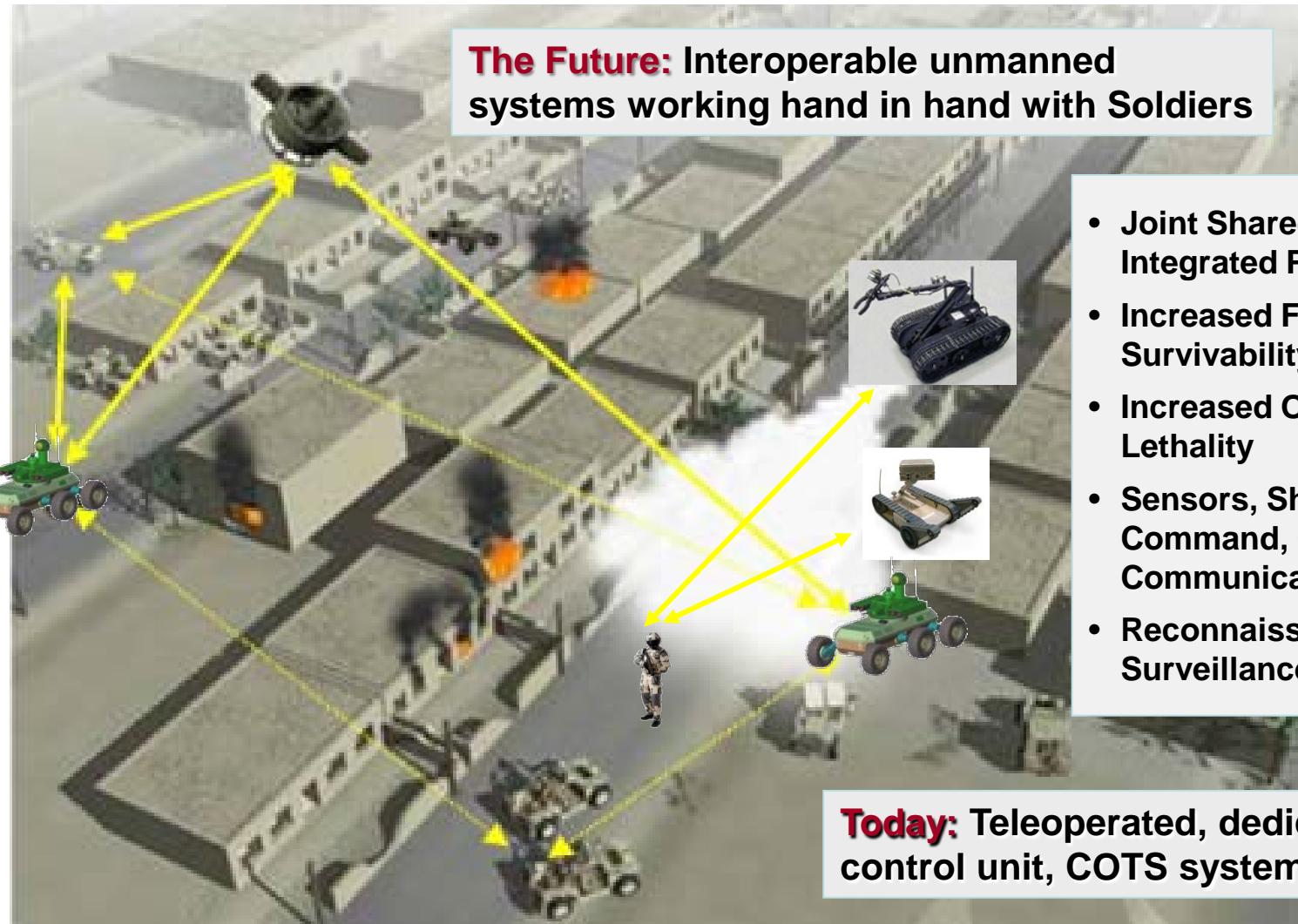
Army Robotics

07 October 2009

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Report Documentation Page			Form Approved OMB No. 0704-0188	
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1. REPORT DATE 07 OCT 2009	2. REPORT TYPE N/A	3. DATES COVERED -		
4. TITLE AND SUBTITLE Army Robots		5a. CONTRACT NUMBER		
		5b. GRANT NUMBER		
		5c. PROGRAM ELEMENT NUMBER		
6. AUTHOR(S) Grant Gerhart; Bernard Theisen		5d. PROJECT NUMBER		
		5e. TASK NUMBER		
		5f. WORK UNIT NUMBER		
7. PERFORMING ORGANIZATION NAME(S) AND ADDRESS(ES) US Army RDECOM-TARDEC 6501 E 11 Mile Rd Warren, MI 48397-5000, USA		8. PERFORMING ORGANIZATION REPORT NUMBER 20248		
9. SPONSORING/MONITORING AGENCY NAME(S) AND ADDRESS(ES)		10. SPONSOR/MONITOR'S ACRONYM(S) TACOM/TARDEC		
		11. SPONSOR/MONITOR'S REPORT NUMBER(S) 20248		
12. DISTRIBUTION/AVAILABILITY STATEMENT Approved for public release, distribution unlimited				
13. SUPPLEMENTARY NOTES The original document contains color images.				
14. ABSTRACT				
15. SUBJECT TERMS				
16. SECURITY CLASSIFICATION OF:			17. LIMITATION OF ABSTRACT SAR	18. NUMBER OF PAGES 25
a. REPORT unclassified	b. ABSTRACT unclassified	c. THIS PAGE unclassified	19a. NAME OF RESPONSIBLE PERSON	



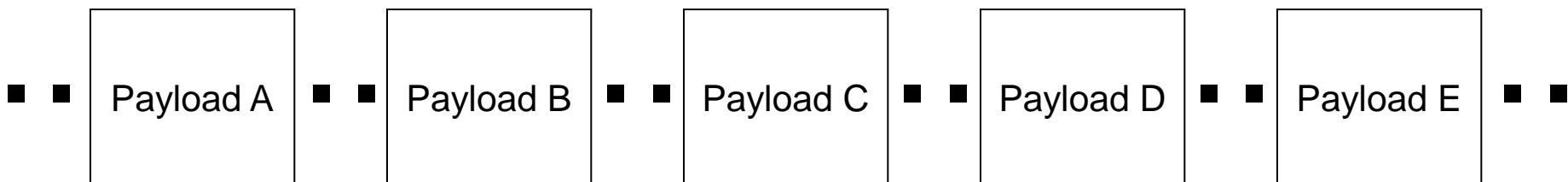


Common payload interface across platforms by mission or class

Family of unmanned ground systems



Payload Interface Standard Architecture



Mission equipment payloads



Maneuver



- IED Defeat Systems
- Disarm / Disrupt
- Reconnaissance
- Investigation
- Explosive Sniffer

Maneuver Support



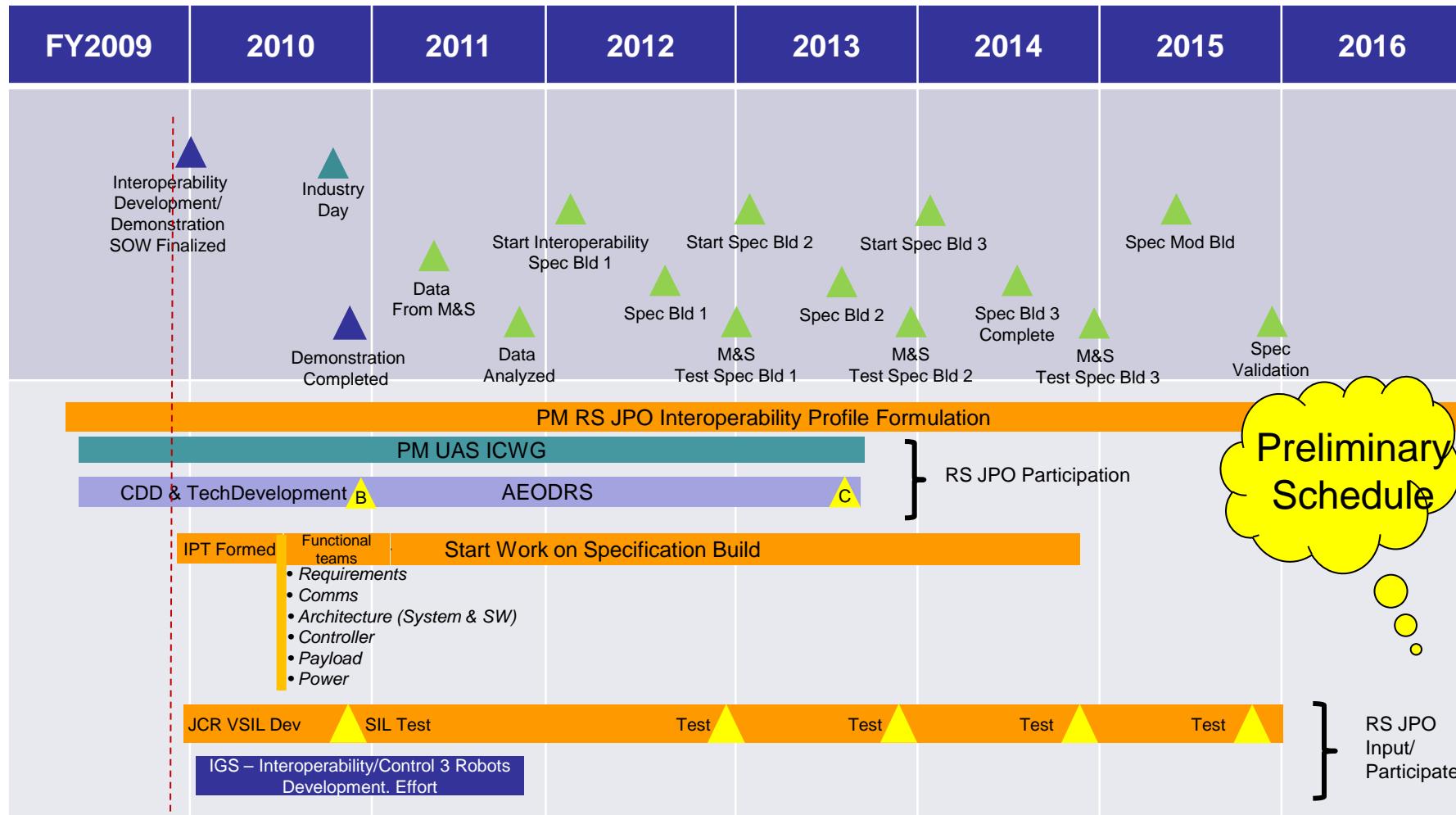
- Area/Route Clearance
- Mine Neutralization
- Counter IED
- CBRNE

Sustainment



- Common Robotic Kit
- EOD
- Convoy
- Log/Resupply

Interoperability Top Level Schedule



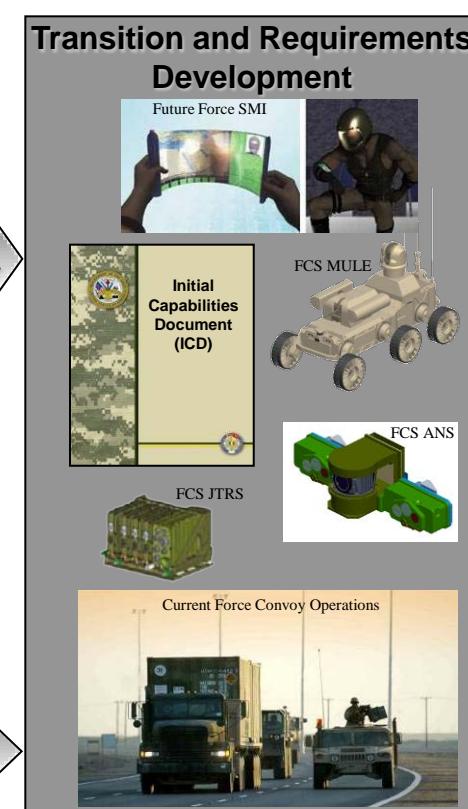
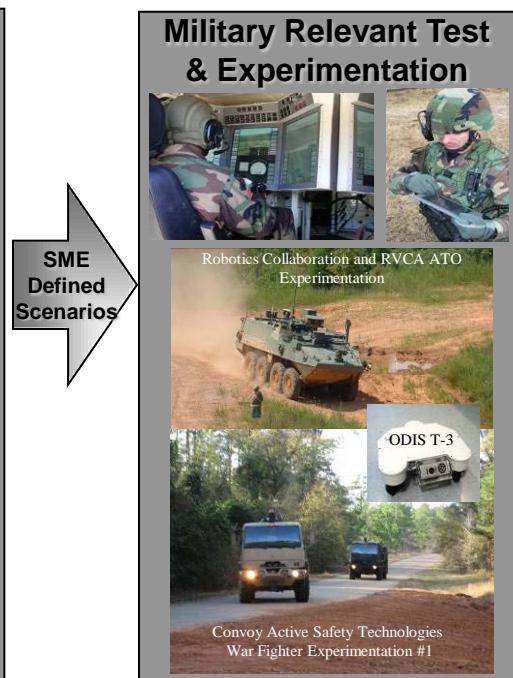
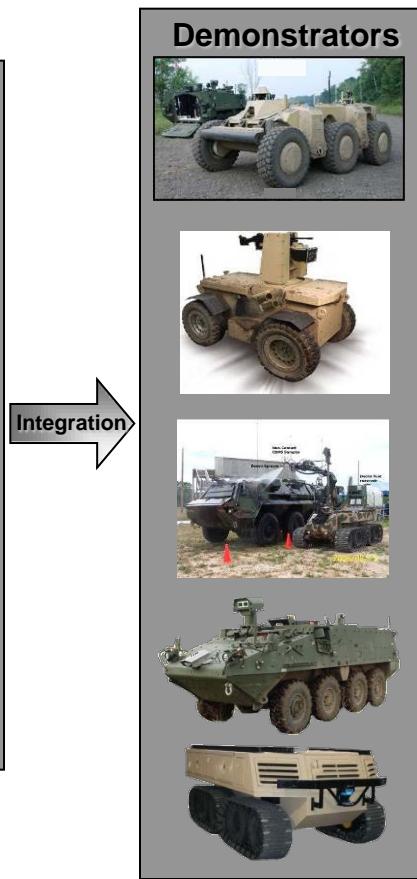
- S&T Support to the RS-JPO
- Develops and Fosters external Relationships
- Matures technology for Insertion into ATO programs
- Robotics Outreach
- RS JPO Collaboration Cell Lead
- Support to IGS Capability Cells
- Robotics Academic Programs (Including Curriculum Development)



Government Partnerships	Industry Partnerships	Academia Partnerships	Community Outreach
       	ABB BAE Delphi Ford General Dynamics General Motors Google iRobot JADI John Deere Lockheed Martin Oshkosh Polaris QinetiQ Quantum Signal Raytheon SoarTechnology Think-A-Move Toyota	Auburn University Carnegie Mellon Lawrence Technological University Massachusetts Institute of Technology Michigan State University Michigan Technological University Oakland University University of Detroit Mercy University of Michigan – Ann Arbor University of Michigan – Dearborn US Military Academy at West Point Virginia Tech Wayne State University	IGVC FIRST Robofest Robotics, Engineering and Technology Days TARDEC Robotics Quarterlies

Mission

Integrate, Explore, and Develop Robotics, Network and Control Components with a Focus on Customer Driven Requirements to Provide Full System Solutions to the War Fighter



Integration Technology Development Lessons Learned to Enable Early Technology Insertion

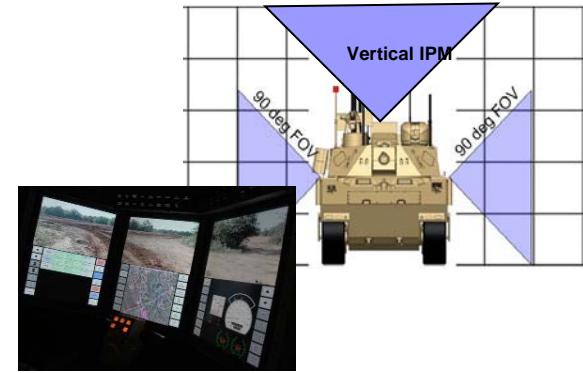
Autonomous Behaviors



Warfighter Support



360° Situational Awareness



UGV Safe Operations



Architecture Development & Demonstration



Human – Robot Interface





**Near Autonomous Unmanned Systems
ATO Capstone**



Convoy Active Safety Technologies (CAST)



**Robotic Vehicle Control Architecture
In collaboration with PM-FCS (BCT)**



Robotics Collaboration ATO Capstone

Under Vehicle Inspections



Remote Mine Detection System

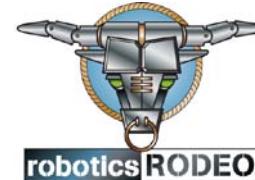


Construction Engineering Robotic Kit



Robotic Decontamination





Autonomous Detection Vehicle

- Autonomous route investigation and hazard marking
- Fundamentally an appliqué kit for Husky
- Funding exists for developmental phase (JIEDDO to NVL)
- Leverage previous work by GDRS for NVL



Manned/Unmanned Teaming (MUT)

- Large armed robotic platform assumes role as a member of squad / formation
- Leverage existing ARDEC, AMREC, CERDEC technologies and Fort Hood rodeo for target acquisition and engagement capability



Convoy Logistics

- Kit-based system for TWV automated leader-follower
- User assessment at Fort Hood in the September – October timeframe
- Funding exists for developmental phase
 - Potential to leverage JCTD for cycle development



Robotics Rodeo

- Input from Army needs (ONS)
- Demonstration of related state of the art technologies
- Provide user and SME feedback to industry

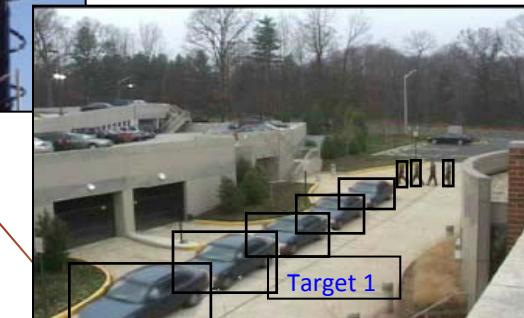
VOIED

- Capability for autonomous VOIED defeat
- Utilize robotic rodeo to demonstrate vendor capabilities

Defeat

Persistent Stare

- Small robot with autonomous navigation to perform recon and surveillance
- Utilize robotic rodeo to demonstrate vendor capabilities





Robotics CTA – Technology for Near Autonomous Systems



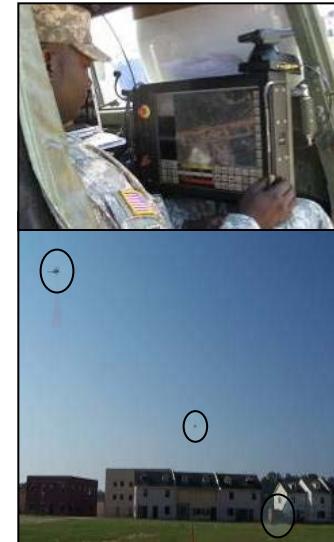
Command & Control of Robotic Entities



Robotic Platform for Engineer Missions



MAST CTA - Small “Creatures for Urban Terrain”



Air-Ground Collaboration

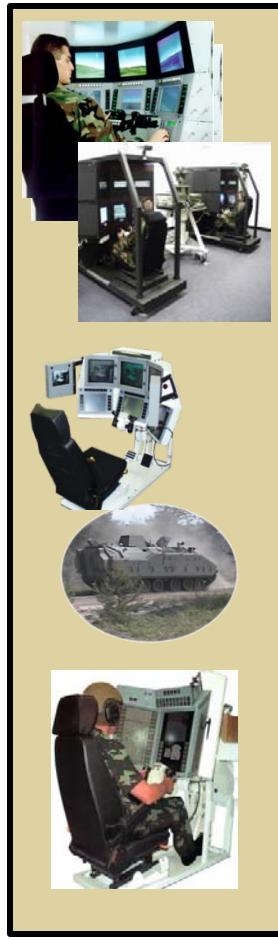


Following, Awareness, SafeOps, and Tracking through IGS (fastIGS)



PAST

- Workload reduction
- Embedded crewstation



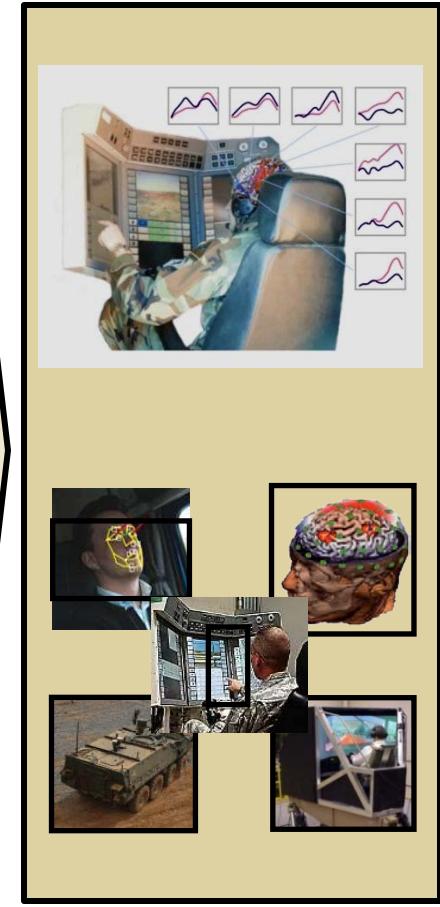
PRESENT

- Robotic control (mounted, dismounted)
- Driving aids (Soldier assist)
- Scalable, portable Interface



FUTURE

- Soldier monitoring and task assist
- Intelligent agents
- 360 degree situational awareness



Purpose: Incorporate actual hardware both fielded and prototypes using simulation, stimulation and emulation to test concepts and validate capabilities.

- **Hardware In The Loop** includes:
 - Vehicle Warfighter Machine Interface
 - Dismounted Controllers
 - FBCB2 and other ABCS
 - SoSCOE
 - Autonomous Control Algorithms

Partners:

- Robotic Systems Joint Project Office (RS-JPO)
- Cross Command Collaboration Effort (3CE)
- Natick Soldier Center – Infantry Warrior Simulation (IWARS)
- Night Vision Labs – Comprehensive Munitions and Sensor Server (CMS2)
- Modeling Architecture for Technology, Research and EXperimentation (MATREX)



**Large****Robotics CTA****Man-packable****Micro****Micro-Autonomous Science & Technology CTA**

Consortium Members

- General Dynamics Robotic Systems (Lead Industrial Partner)
- Carnegie Mellon University
- Applied Systems Intelligence
- Jet Propulsion Laboratory
- Alion Science & Technology
- BAE Systems
- Sarnoff Corporation
- SRI International
- Florida A&M University
- University of Maryland
- PercepTek
- Robotic Research
- Signal Systems Corp
- Howard University
- NC A&T University
- University of Pennsylvania
- Skeyes Unlimited
- Johns Hopkins University

Objectives

Make the research investments that support the Army's robotic system development goals:

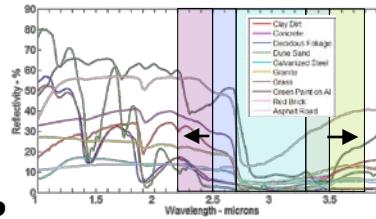
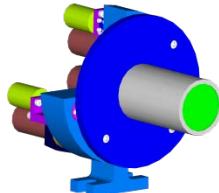
- *Develop perception technologies that allow robotic vehicles to sense and understand their environment;*
- *Develop intelligent control technologies and architectures enabling robotic systems to autonomously plan, execute, and monitor operational tasks undertaken in complex, tactical environments;*
- *Develop human-machine interfaces that allow soldiers to effectively task robotic systems and minimize operator workload.*

Technical Areas

- Advanced Perception
- Intelligent Control & Behavior Development
- Human / Machine Interfaces



Exploration of novel sensor modes



**Novel LADAR
for small systems**

Spectral LADAR

...to expand applicability and enhance available information

Moving Agent Understanding



Different postures

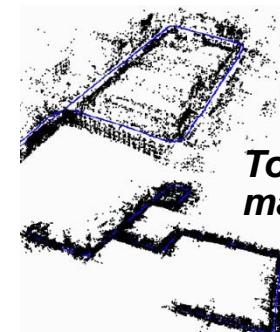
Goal is fusion of multiple techniques to improve accuracy and robustness

In clutter & complexity

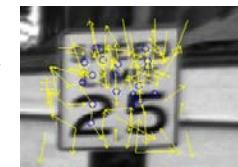
Improved environmental understanding, especially for dynamic environments

- Application of learning techniques

Terrain Classification



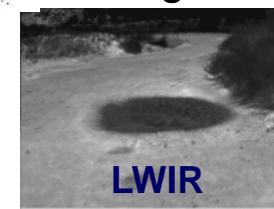
**Topologic
maps**



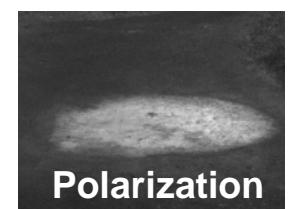
Road Features



RGB



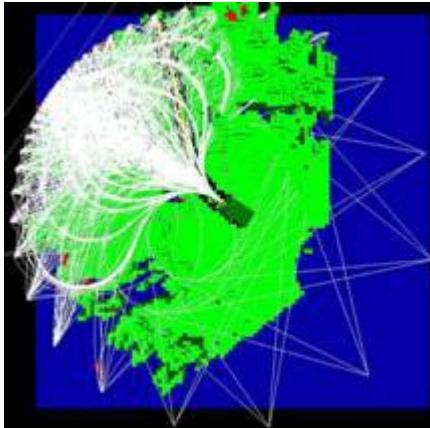
LWIR



Polarization

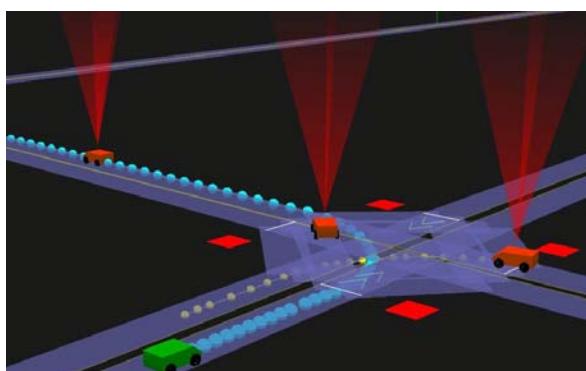
Examining methods for real-time planning and execution of complex missions

Integration of multiple planners for real-time operation



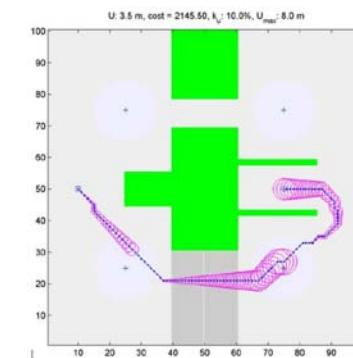
Off-road

High Mobility

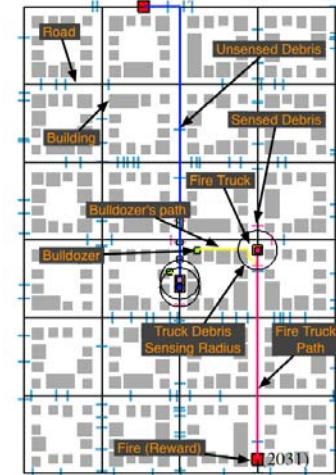


On-road

Planning with uncertainty



...and time constraints



Full implementation of multi-layer planning

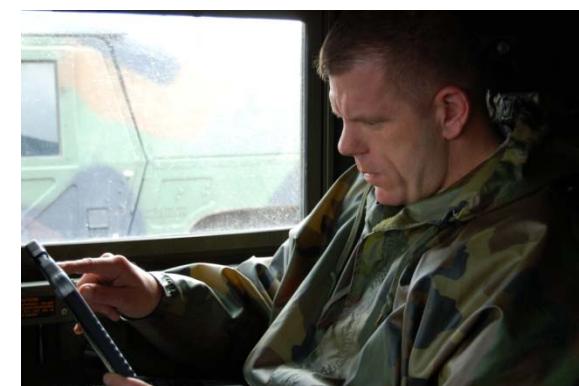


Dynamic Replanning Example

Scalable Human Machine Interfaces



...and Multi-Modal Input



... to reduce soldier cognitive workload

Unmanned Systems become another soldier in the unit:

highly capable with scalable attributes to meet mission requirements; requiring reduced communication and minimal soldier interaction; flexible, robust, and reliable; able to adapt fully to new & different tactical and environmental conditions; following commanders intent; effectively operating in mixed environments; able to “learn from experience; maneuvering unfettered in complex terrain; able to “live” in a world designed for humans, to grasp small objects, to open doors, or to carry the wounded.

- What missions will they conduct ?**
- What level of capability?**
- What degree of autonomy will they possess?**
- How will they work with soldiers ?**
- Or function in general society?**
- How will they be used in Urban operations?**
- In complex terrain?**
- How will they navigate in GPS denied environments ?**



Perceive & understand a dynamic & unknown environment



- Sensors
- Information Fusion
- Perception Algorithms
- All environments
- All scales
- Relevant world model

- Sensing

- Greater resolution & range, lower cost
- Increased fields of view; focus of attention
- Scale
- All weather/environments

- Terrain/Object Understanding

- Broader vocabulary
- Recognition of cues/saliency of observations
- Robust & adaptive
- Reasoning
- Fusion

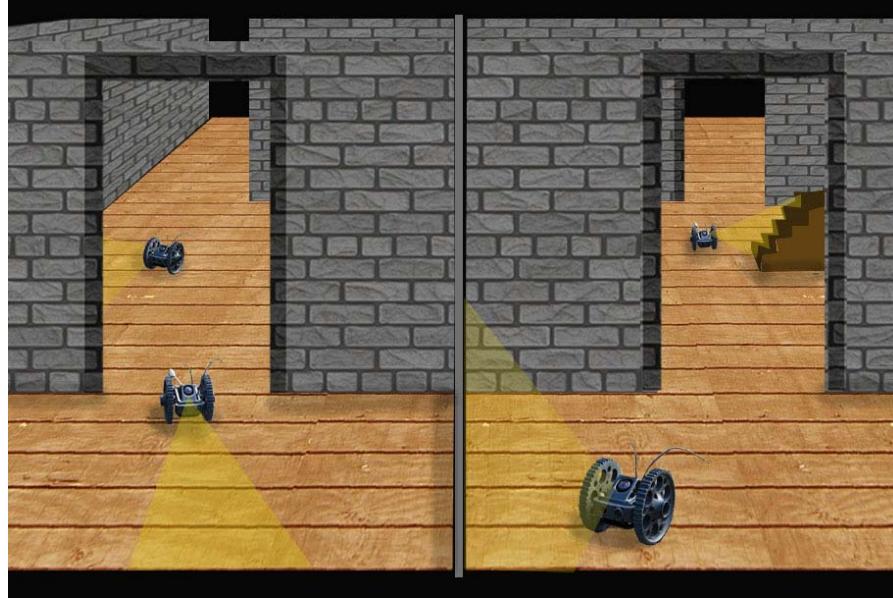
- Understanding activity

- Human activity/intent recognition
- Saliency of observations/ context & cues
- Learning

- World model

- Managed & validated
- Long-term & short-term memory
- Collaborative or distributed
- Common ground (HRI)
- Navigation (Intelligence, mobility & manipulation)

Plan and execute military tasks & missions



- Robust
- Adaptive
- Learns from Experience
- Transparent

Some potential research topics

- Learn & Adapt
 - Deductive reasoning
 - Inference
 - Generalization/Rules of engagement
 - Uncertainty of future conditions
 - Probabilistic reasoning
 - Spatial & temporal reasoning
- Self-awareness/introspection
 - Transparency
 - Providing non-verbal cues
 - Human-robot collaboration
 - Fault detection
- World model
 - Common ground
 - Mixed initiative
- Scale
 - Adapting to resource limitations
- Tactically intelligent behavior
- Collaboration between homogeneous & heterogeneous systems

Seamless integration of robots into military & civilian activity



- **Effective Control of multiple systems**
- **Human-robot Teaming**
- **Seamless integration of robots & society**

Some potential research topics

- **Shared situational awareness**
 - Aware of cultural and behavioral norms.
 - Comprehend commander's intent & act upon it
 - Understand the intent of surrounding humans for consideration in planning
 - Possess common spatial & temporal frames of reference – a “common ground”
- **Trust & Confidence**
 - Transparency of action
 - Cues to activity
 - Tolerance to failure
- **Intuitive Communication**
 - Language – unconstrained dialogue
 - Non-verbal cues, gestures, context, & behavior
- **Operating within society**
 - Adaptable to varying social cues & context
- **Span of control**

- ***Unmanned Systems will have a major impact on future military operations***
- ***The technology is still in its nascent stages – the Army has made a firm commitment to its development***
- ***The first systems, albeit teleoperated are already impacting current operations***
- ***The first systems with significant autonomy will be fielded over the next 5 – 10 years***
- ***How the Army employs the technology will, as much as the technology itself, determine its future impact***



